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Understanding, improving and parallelizing MUS finding using model rotation

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Minimal Unsatisfiable

- ▶ Finding Minimal Unsatisfiable Subsets (MUSes) in unsatisfiable CNF formulas
- ▶ An unsatisfiable formula \mathcal{F} is minimal unsatisfiable iff any proper subset of its clauses $\mathcal{F}' \subset \mathcal{F}$ is satisfiable.
- ▶ An **assoc** for a clause $c \in \mathcal{F}$ is a complete assignment that satisfies all clauses in \mathcal{F} except c .
- ▶ A formula \mathcal{F} is minimal unsatisfiable iff every clause in the formula has at least one assoc.

Classical destructive algorithm

1. $M = \emptyset$
2. while $\mathcal{F} \neq M$
3. pick a clause $c \in \mathcal{F} \setminus M$
4. if $\mathcal{F} \setminus \{c\}$ is satisfiable then
5. $M = M \cup \{c\}$
6. else
7. $\mathcal{F} = \mathcal{F} \setminus \{c\}$
8. return \mathcal{F}

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4. if $\mathcal{F} \setminus \{c\}$ is satisfiable then
5. $M = M \cup \{c\}$
- ⇒ modelRotate(c, a) // (a =sat. assign. for $\mathcal{F} \setminus \{c\}$)
6. else
7. $\mathcal{F} = \mathcal{F}'$ s.t. \mathcal{F}' is unsatisfiable and $\mathcal{F}' \subseteq \mathcal{F} \setminus \{c\}$
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Model rotation

Marques-Silva and Lynce, SAT2011

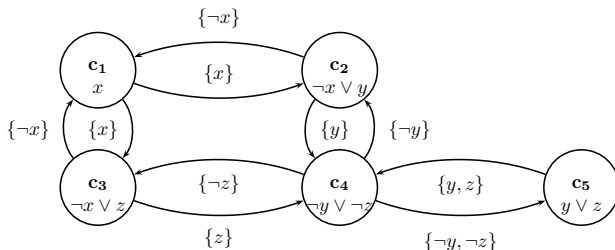
Belov and Marques-Silva, FMCAD2011

function modelRotate(*clause* c , *assignment* a)

1. for all $l \in c$ do
2. $a' = a$ except l is assigned **true** instead of **false**
3. if $\left(\begin{array}{l} \text{exactly one clause } c' \in \mathcal{F} \text{ is} \\ \text{not satisfied by } a' \text{ and } c' \notin M \end{array} \right)$ then
4. $M = M \cup \{c'\}$
5. modelRotate(c' , a')

Flip graph

- ▶ A vertex for every clause
- ▶ Edges are labelled: $L(c_i, c_j) = \{l \mid l \in c_i \text{ and } \neg l \in c_j\}$
- ▶ An edge between c_i and c_j iff $L(c_i, c_j) \neq \emptyset$



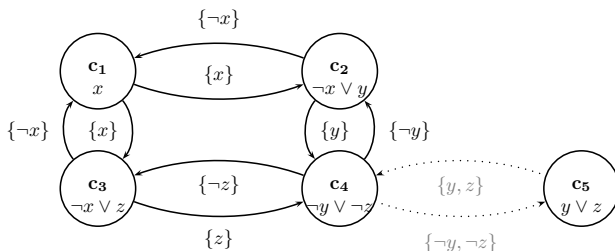
Flip graph

- ▶ Lemma 1:

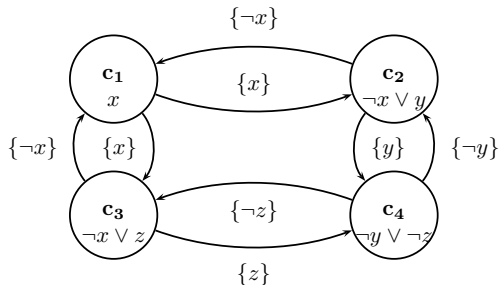
*Rotating literal l in an assoc for a clause c_i can **not** result in an assoc for clause c_j if $L(c_i, c_j) \neq \{\neg l\}$*

- ▶ Possible rotation edges:

All edges (c_i, c_j) for which $|L(c_i, c_j)| = 1$

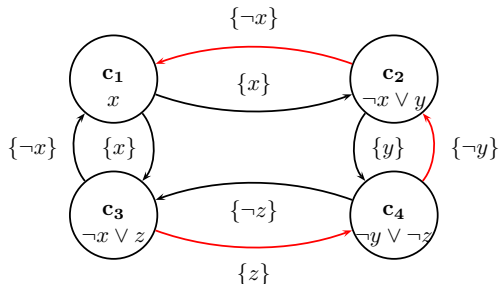


Rotation example



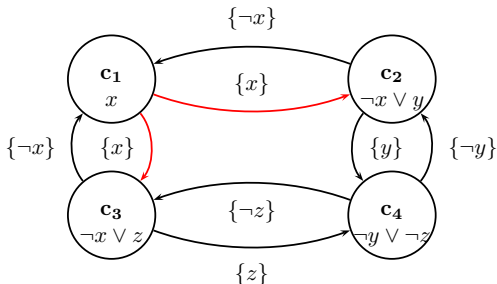
assoc for: c_3 $x = \mathbf{true}$ $y = \mathbf{true}$ $z = \mathbf{false}$

Rotation example



assoc for: c ₃	$x = \mathbf{true}$	$y = \mathbf{true}$	$z = \mathbf{false}$
assoc for: c ₄	$x = \mathbf{true}$	$y = \mathbf{true}$	$z = \mathbf{true}$
assoc for: c ₂	$x = \mathbf{true}$	$y = \mathbf{false}$	$z = \mathbf{true}$
assoc for: c ₁	$x = \mathbf{false}$	$y = \mathbf{false}$	$z = \mathbf{true}$

Rotation example



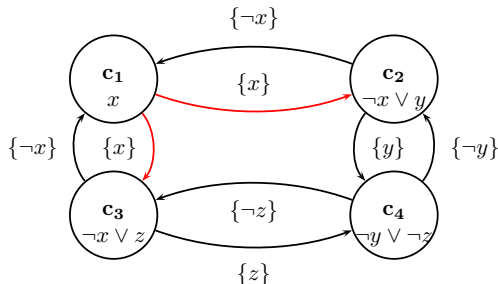
There are 3 possible assocs for c_1 .

$x=\text{false}$ $y=\text{false}$ $z=\text{true}$

$x=\text{false}$ $y=\text{true}$ $z=\text{false}$

$x=\text{false}$ $y=\text{false}$ $z=\text{false}$

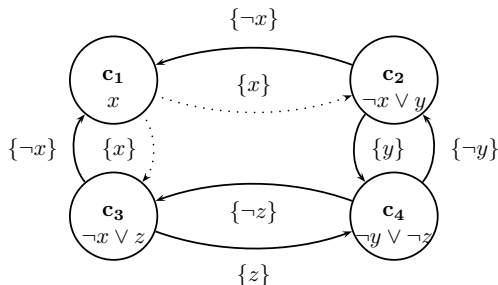
Rotation example



There are 3 possible assocs for c_1 . Rotation gives:

- $x=\mathbf{true}$ $y=\mathbf{false}$ $z=\mathbf{true}$ \rightarrow assoc for c_2
- $x=\mathbf{true}$ $y=\mathbf{true}$ $z=\mathbf{false}$ \rightarrow assoc for c_3
- $x=\mathbf{true}$ $y=\mathbf{false}$ $z=\mathbf{false}$ \rightarrow does not satisfy c_2 and c_3 !

Rotation example



- Guaranteed rotation edges:

All possible rotation edges (c_i, c_j) s.t. for all $c_k \neq c_j$ it holds that $L(c_i, c_j) \neq L(c_i, c_k)$

Rotation theory

- ▶ Theorem 1:

If c_i has an assoc and a guaranteed rotation edge (c_i, c_j) exist then c_j has an assoc

- ▶ If c_i has an assoc and a path over guaranteed rotation edges from c_i to c_j exist then c_j has an assoc

- ▶ Corollary 1:

If a path over guaranteed rotation edges between c_i and c_j exists in both directions then c_i has an assoc iff c_j has an assoc

Strongly Connected Components

- ▶ A directed graph is *strongly connected* if there exists a path between any two of its vertices
- ▶ The *strongly connected components* (SCCs) of a directed graph are its maximal strongly connected subgraphs

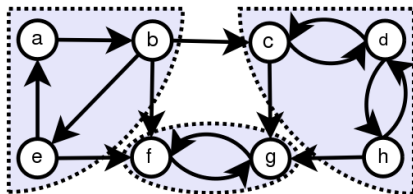


Figure source: http://en.wikipedia.org/wiki/Strongly_connected_component

Rotation theory continued

- ▶ Let \mathcal{F} be an unsatisfiable formula
- ▶ Let E_G be the set of guaranteed rotation edges \mathcal{F} induces
- ▶ Consider the SCCs of the graph $G = (\mathcal{F}, E_G)$
- ▶ Corollary 2:
A MUS $\mathcal{F}' \subseteq \mathcal{F}$ can be found using no more SAT solver calls than there are SCCs in $G = (\mathcal{F}, E_G)$

Rotation theory continued

- ▶ Let a *root SCC* be an SCC that contains no vertices with incoming edges originating outside the SCC
- ▶ Let \mathcal{F}' be an *minimal unsatisfiable* formula, and E'_G the set of guaranteed rotation edges it induces

- ▶ Corollary 3:

An assoc can be found for every clause in \mathcal{F}' using no more SAT solver calls than there are root SCCs in $G' = (\mathcal{F}', E'_G)$

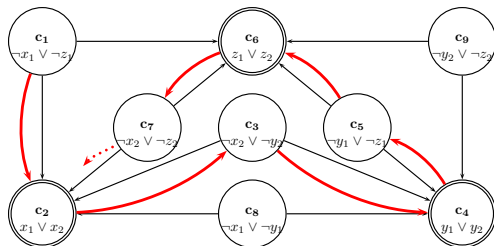
Statistics - benchmarks from Marques-Silva et.al.

	original	MUSes
# benchmarks	500	491
# with single root SCC	148	148
avg. # clauses	6874.4	6204.2
avg. # SCCs	3000.4 (44%)	2484.1 (40%)
avg. # root SCCs	2124.7	1680.5 (27%)
avg. clause length	2.32	2.35
avg. out-degree E_P	12.30	11.24
avg. out-degree E_G	1.60	1.63

Statistics - benchmarks from SAT11 competition

	original		MUSEs	
# benchmarks	298		262	
# with single root SCC	0		51	
avg. # clauses	404574		8162.7	
avg. # SCCs	327815	(81%)	3355.6	(41%)
avg. # root SCCs	258350		1891.1	(23%)
avg. clause length	2.53		2.42	
avg. out-degree E_P	86.84		14.16	
avg. out-degree E_G	0.89		1.59	

Improving & Parallelizing



- ▶ The suggested improvement for model rotation concerns cyclic paths.
- ▶ The parallelization uses the *Tarmo* parallel incremental SAT solver.

Conclusions

- ▶ This work provides new insights on *model rotation*
- ▶ The key is to look at the algorithm as a graph search
- ▶ Typical benchmarks have properties that guarantee effectiveness of model rotation
- ▶ The technique was improved, parallelized and evaluated

- Algorithm 1: Uses standard recursive model rotation.
- Algorithm 2: Uses the SCC graph for choosing clauses c to check in next SAT call

Algorithm 1. MUS finder with recursive model rotation [2,13]

Given an unsatisfiable formula \mathcal{F} :

1. $M = \emptyset$
2. **while** $\mathcal{F} \neq M$
3. **pick** a clause $c \in \mathcal{F} \setminus M$
4. **if** $\mathcal{F} \setminus \{c\}$ is satisfiable **then**
5. $M = M \cup \{c\}$
6. modelRotate(c, a) where a is a compl. satisfying assign. for $\mathcal{F} \setminus \{c\}$
7. **else**
8. $\mathcal{F} = \mathcal{F} \setminus \{c\}$
9. **return** \mathcal{F}

function modelRotate(**clause** c , **assignment** a) // such that $a \in A(c, \mathcal{F})$

- I **for all** $l \in c$ **do**
 - II $a' = \text{rotate}(a, \neg l)$
 - III **if** exactly one clause $c' \in \mathcal{F}$ is not satisfied by a' and $c' \notin M$ **then**
 - IV $M = M \cup \{c'\}$
 - V modelRotate(c', a')
-

Algorithm 2. MUS finder respecting upper bounds of Cor. 2 and Cor. 3

Given an unsatisfiable formula \mathcal{F} and the set E_G it induces:

1. Let $S = \{\mathcal{F}_1, \mathcal{F}_2, \dots, \mathcal{F}_{|S|}\}$ the division of \mathcal{F} into the SCCs of $G = (\mathcal{F}, E_G)$
 2. $M = \emptyset$
 3. **while** $\mathcal{F} \neq M$
 4. **pick** $\mathcal{F}_i \in S$ corresponding to a root SCC such that $M \cap \mathcal{F}_i = \emptyset$
 5. **pick** a clause $c \in \mathcal{F}_i$
 6. **if** $\mathcal{F} \setminus \{c\}$ is satisfiable **then**
 7. $M = M \cup \{c' \mid c' = c \text{ or } c' \text{ is reachable from } c \text{ in } G = (\mathcal{F}, E_G)\}$
 8. **else**
 9. $\mathcal{F} = \mathcal{F} \setminus \mathcal{F}_i$
 10. $S = S \setminus \{\mathcal{F}_i\}$
 11. **return** \mathcal{F}
-

Table 3. Instances solved and average solver calls over benchmarks solved by all

Model rotation	none			standard			improved		
	#	SAT	UNSAT	#	SAT	UNSAT	#	SAT	UNSAT
Alg. 1	-	-	-	136	2696.8	193.4	136	2346.1	188.3
Alg. 2	106	4389.2	162.5	123	3610.8	163.6	131	2341.9	172.4
Alg. 1 Tarmo 4	-	-	-	-	-	-	134	2660.9(88%)	436.0(42%)
Alg. 2 Tarmo 4	-	-	-	-	-	-	135	2448.4(95%)	377.2(43%)
Alg. 1 Tarmo 8	-	-	-	-	-	-	136	2963.0(79%)	796.5(23%)
Alg. 2 Tarmo 8	-	-	-	-	-	-	139	2605.7(90%)	700.6(23%)

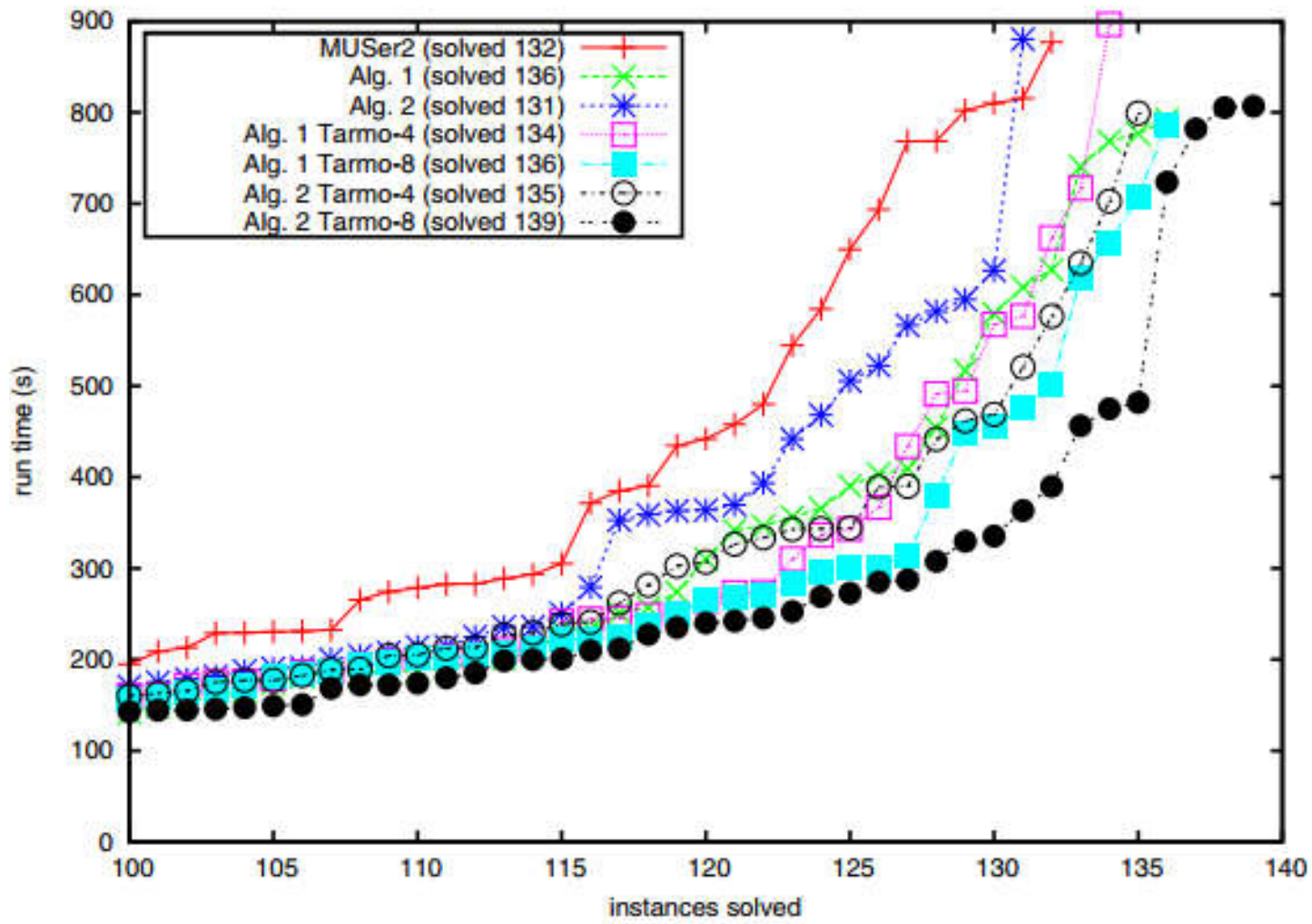


Fig. 3. Comparison of multiple versions

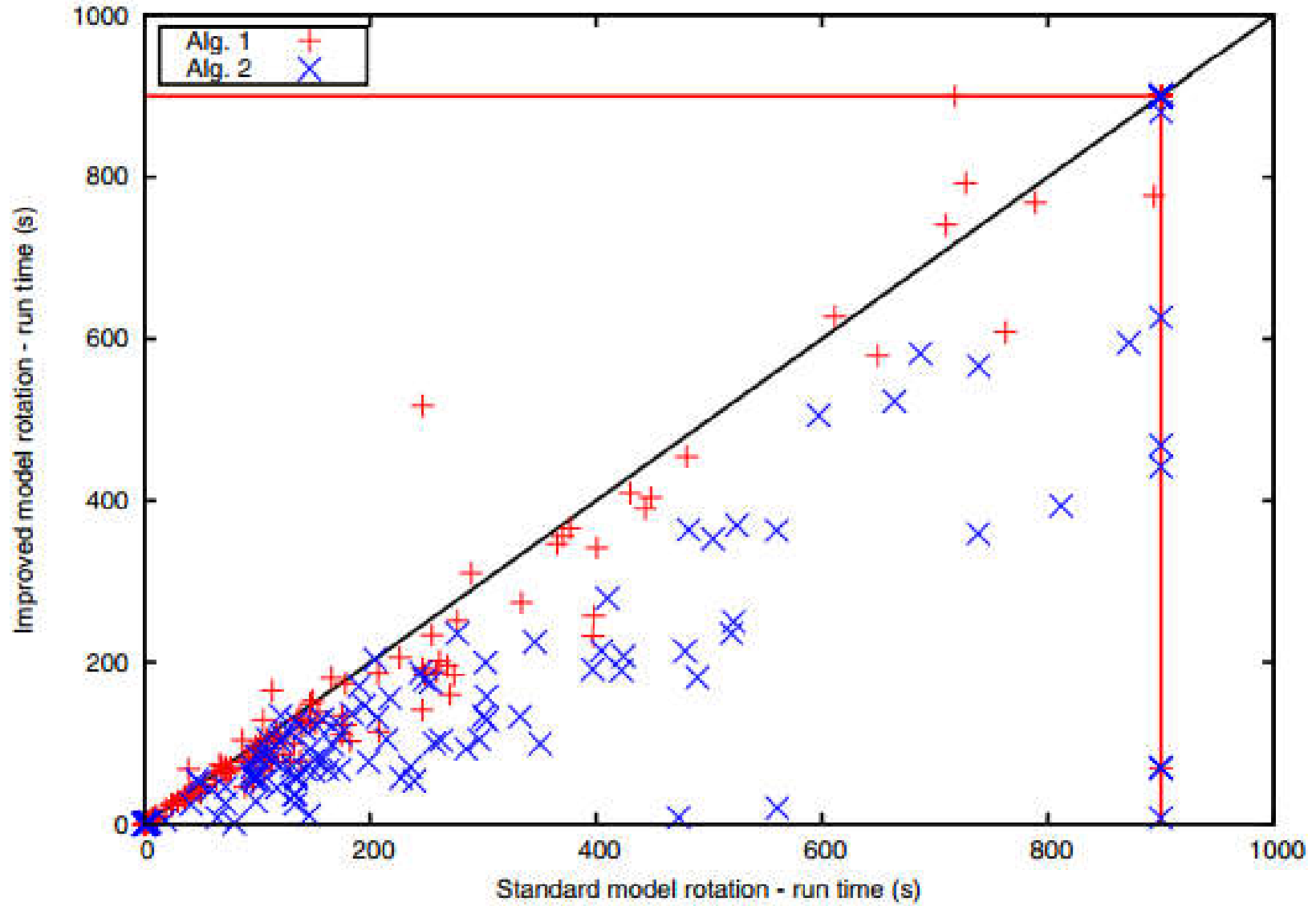


Fig. 4. Effect of improved model rotation

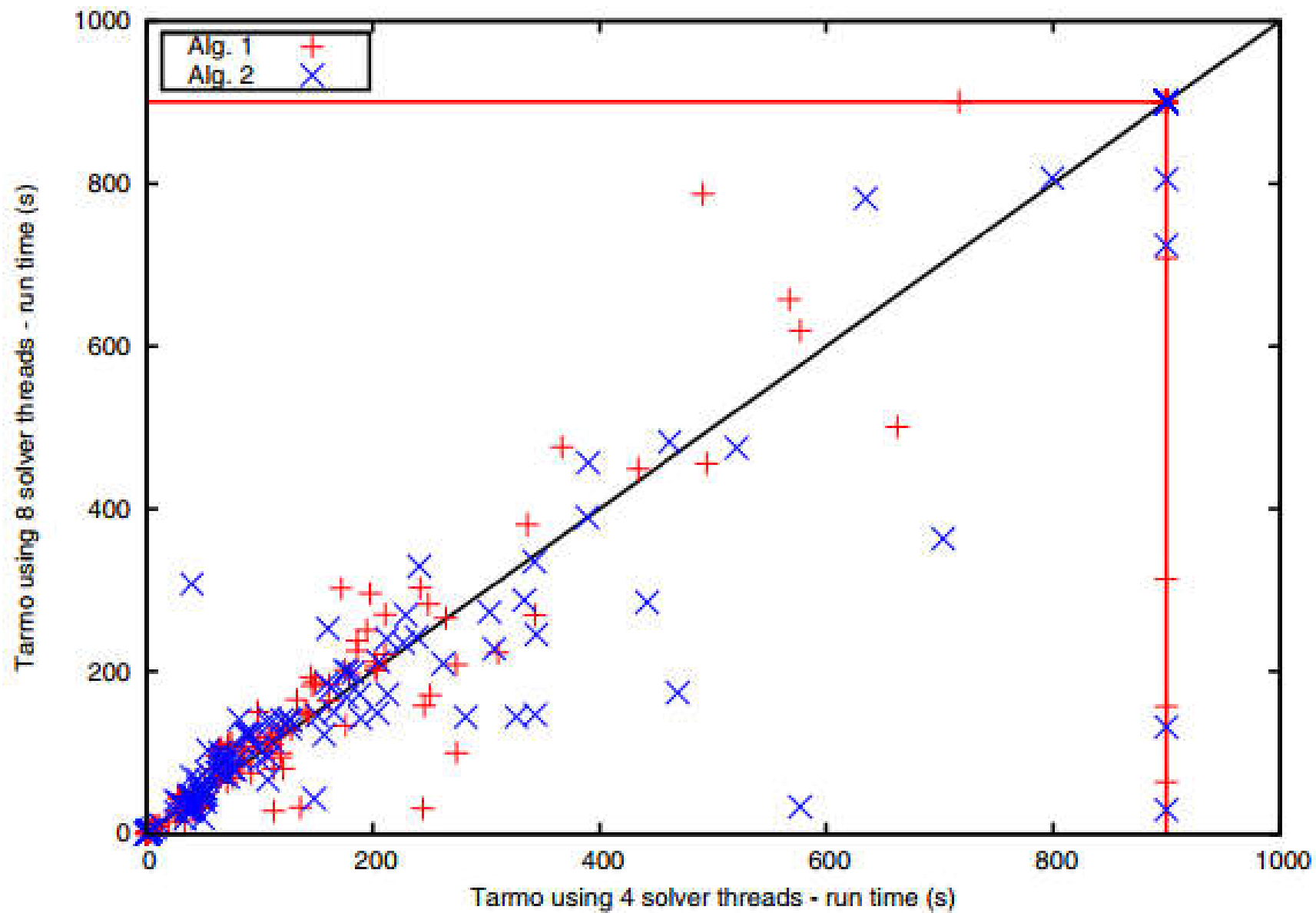


Fig. 5. Performance of 4 versus 8-threads